



Time Series Analysis

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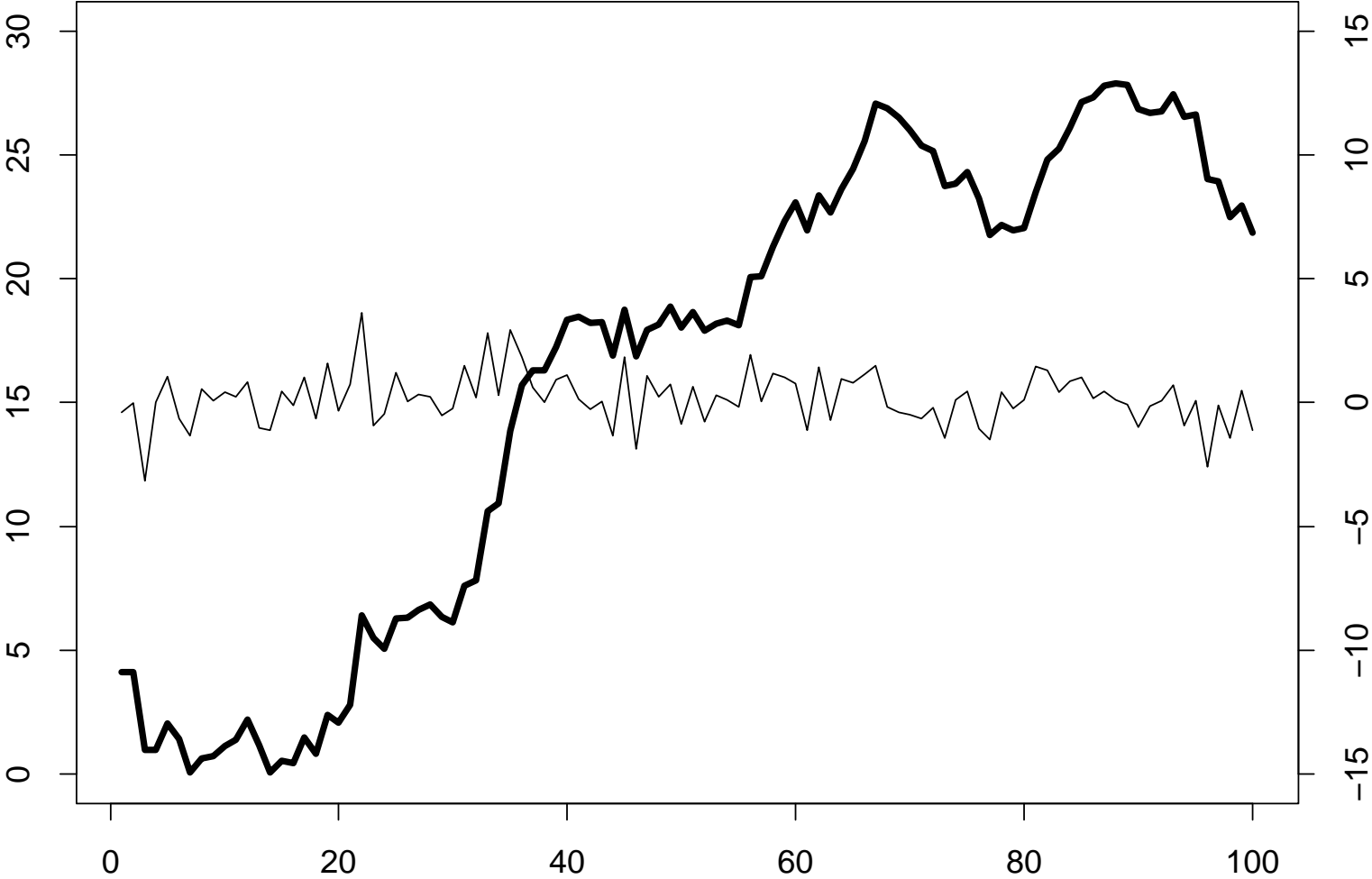
Outline of the lecture

Stochastic processes, 2nd part:

- Non-stationary models, Sec. 5.6
- Optimal Prediction, Sec. 5.7



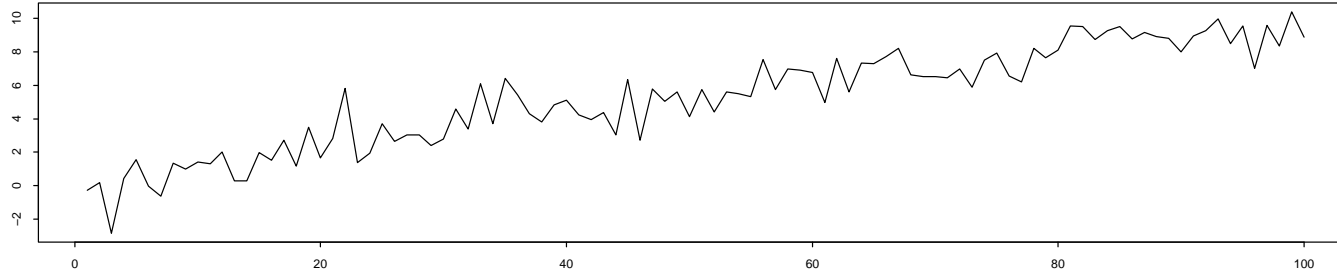
Non-stationary series



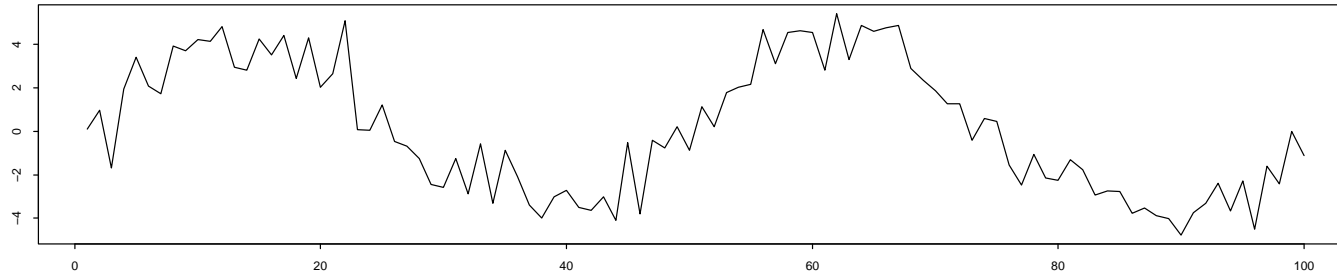


Some types of non-stationarity

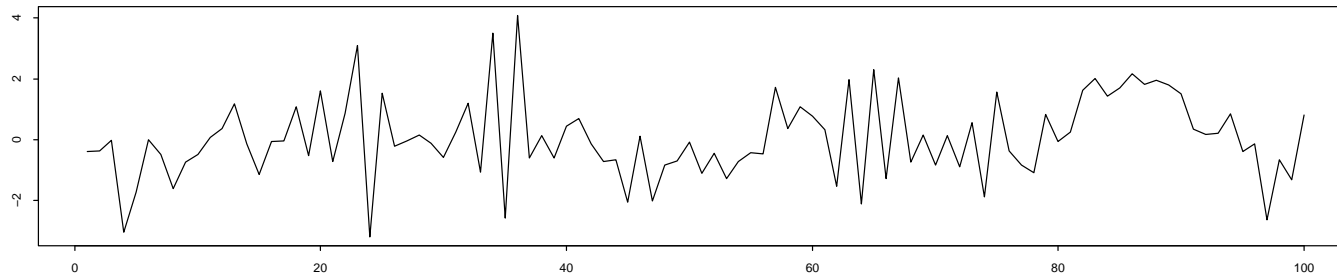
Long term trends



Periodic trends



General time varying behavior





The $ARIMA(p, d, q)$ -process

- An $ARMA(p, q)$ model for:

$$W_t = \nabla^d Y_t = (1 - B)^d Y_t$$

where $\{Y_t\}$ is the series

- That is:

$$\phi(B)\nabla^d Y_t = \theta(B)\varepsilon_t$$

- If we consider stationarity:

$$\phi(z^{-1})(1 - z^{-1})^d = 0$$

i.e. d roots in $z = 1 + 0i$, and the rest inside the unit circle



The $(p, d, q) \times (P, D, Q)_s$ seasonal process

- A multiplicative (stationary) $ARMA(p, q)$ model for:

$$W_t = \nabla^d \nabla_s^D Y_t = (1 - B)^d (1 - B^s)^D Y_t$$

where $\{Y_t\}$ is the series

- That is:

$$\phi(B)\Phi(B^s)\nabla^d \nabla_s^D Y_t = \theta(B)\Theta(B^s)\varepsilon_t$$

- If we consider stationarity:

$$\phi(z^{-1})(1 - z^{-1})^d (1 - z^{-s})^D = 0$$

i.e. d roots in $z = 1 + 0i$, $D \times s$ roots on the unit circle, and the rest inside the unit circle



The case $d = D = 0$; stationary seasonal process

- General:

$$\phi(B)\Phi(B^s)Y_t = \theta(B)\Theta(B^s)\varepsilon_t$$

- Example:

$$(1 - \Phi B^{12})Y_t = \varepsilon_t$$

- Which can also be written:

$$Y_t = \Phi Y_{t-12} + \varepsilon_t$$

i.e. Y_t depend on Y_{t-12} , Y_{t-24} , ... (thereof the name)

- How would you think that the auto covariance function looks?
- Take a look at Example 5.10 also.



Prediction

- At time t we have observations $Y_t, Y_{t-1}, Y_{t-2}, Y_{t-3}, \dots$
- We want a prediction of Y_{t+k} , where $k \geq 1$
- If we want to minimize the expected squared error the optimal prediction is the conditional expectation:

$$\hat{Y}_{t+k|t} = E[Y_{t+k} | Y_t, Y_{t-1}, Y_{t-2}, \dots]$$



Example – prediction in the $AR(1)$ model

- We write the model like $Y_{t+1} = \phi Y_t + \varepsilon_{t+1}$ (note the sign on ϕ)
- 1-step prediction:

$$\begin{aligned}\hat{Y}_{t+1|t} &= E[Y_{t+1}|Y_t, Y_{t-1}, \dots] = E[\phi Y_t + \varepsilon_{t+1}|Y_t, Y_{t-1}, \dots] \\ &= \phi Y_t + 0 = \phi Y_t\end{aligned}$$

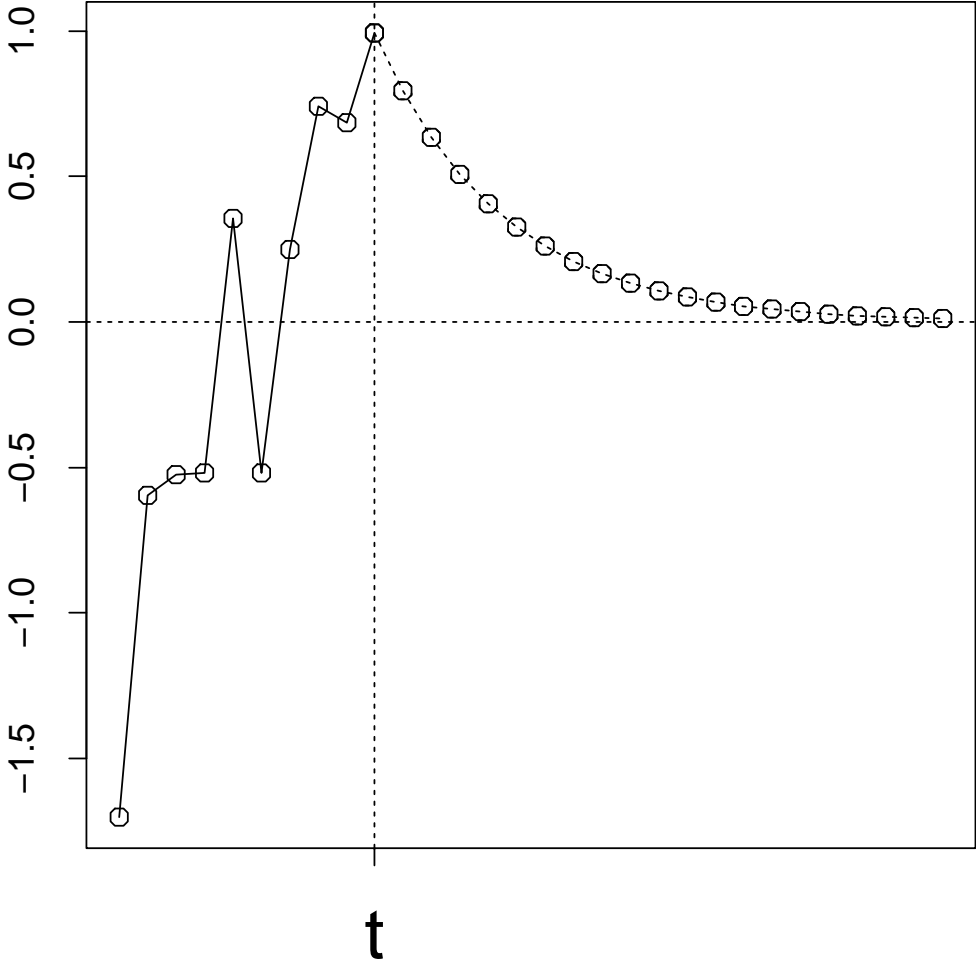
- 2-step prediction:

$$\begin{aligned}\hat{Y}_{t+2|t} &= E[Y_{t+2}|Y_t, Y_{t-1}, \dots] = E[\phi Y_{t+1} + \varepsilon_{t+2}|Y_t, Y_{t-1}, \dots] \\ &= \phi \hat{Y}_{t+1|t} + 0 = \phi^2 Y_t\end{aligned}$$

- k-step prediction: $\hat{Y}_{t+k|t} = \phi^k Y_t$



Example – prediction in $Y_t = 0.8Y_{t-1} + \varepsilon_t$





Variance of prediction error for the $AR(1)$ -process

Prediction error:

$$e_{t+k|t} = Y_{t+k} - \hat{Y}_{t+k|t} = Y_{t+k} - \phi^k Y_t$$

$$\begin{aligned} Y_{t+k} &= \phi Y_{t+k-1} + \varepsilon_{t+k} \\ &= \phi(\phi Y_{t+k-2} + \varepsilon_{t+k-1}) + \varepsilon_{t+k} \\ &= \phi^2 Y_{t+k-2} + \phi \varepsilon_{t+k-1} + \varepsilon_{t+k} \\ &= \phi^2(\phi Y_{t+k-3} + \varepsilon_{t+k-2}) + \phi \varepsilon_{t+k-1} + \varepsilon_{t+k} \\ &= \phi^3 Y_{t+k-3} + \phi^2 \varepsilon_{t+k-2} + \phi \varepsilon_{t+k-1} + \varepsilon_{t+k} \\ &\vdots \\ &= \phi^k Y_t + \phi^{k-1} \varepsilon_{t+1} + \phi^{k-2} \varepsilon_{t+2} + \dots + \phi \varepsilon_{t+k-1} + \varepsilon_{t+k} \end{aligned}$$



Variance of prediction error for the $AR(1)$ -process

Variance of prediction error:

$$\begin{aligned} V[e_{t+k|t}] &= V[\phi^{k-1}\varepsilon_{t+1} + \phi^{k-2}\varepsilon_{t+2} + \dots + \phi\varepsilon_{t+k-1} + \varepsilon_{t+k}] \\ &= (\phi^{2(k-1)} + \phi^{2(k-2)} + \dots + \phi^2 + 1)\sigma_\varepsilon^2 \end{aligned}$$

$(1 - \alpha) \times 100\%$ prediction interval:

$$\hat{Y}_{t+k|t} \pm u_{\alpha/2} \sqrt{V[e_{t+k|t}]}$$

$u_{\alpha/2}$ is the $\alpha/2$ -quantile in the standard normal distribution



k -step prediction in $ARMA(p, q)$ -models

The process:

$$Y_{t+k} + \phi_1 Y_{t+k-1} + \cdots + \phi_p Y_{t+k-p} = \varepsilon_{t+k} + \theta_1 \varepsilon_{t+k-1} + \cdots + \theta_q \varepsilon_{t+k-q}$$

Using conditional expectation on both sides we get:

$$\begin{aligned} \hat{Y}_{t+k|t} &= -\phi_1 \hat{Y}_{t+k-1|t} - \cdots - \phi_p \hat{Y}_{t+k-p|t} \\ &\quad + \hat{\varepsilon}_{t+k|t} + \theta_1 \hat{\varepsilon}_{t+k-1|t} + \cdots + \theta_q \hat{\varepsilon}_{t+k-q|t} \end{aligned}$$

This results in a recursive method for calculating the predictions – how would you find $\varepsilon_{t+k-q|t}$?



Inverse form

For an invertible process, the π -weights

$$\varepsilon_t = Y_t + \pi_1 Y_{t-1} + \pi_2 Y_{t-2} + \dots$$

goes to zero sufficiently fast and only recent values of the process is needed.



Variance of prediction error

Process written with ψ -weights:

$$Y_{t+k} = \varepsilon_{t+k} + \psi_1 \varepsilon_{t+k-1} + \cdots + \psi_k \varepsilon_t + \psi_{k+1} \varepsilon_{t-1} + \cdots$$

k -step prediction:

$$\hat{Y}_{t+k|t} = \psi_k \varepsilon_t + \psi_{k+1} \varepsilon_{t-1} + \cdots$$

k -step prediction error:

$$e_{t+k|t} = Y_{t+k} - \hat{Y}_{t+k|t} = \varepsilon_{t+k} + \psi_1 \varepsilon_{t+k-1} + \cdots + \psi_{k-1} \varepsilon_{t+1}$$

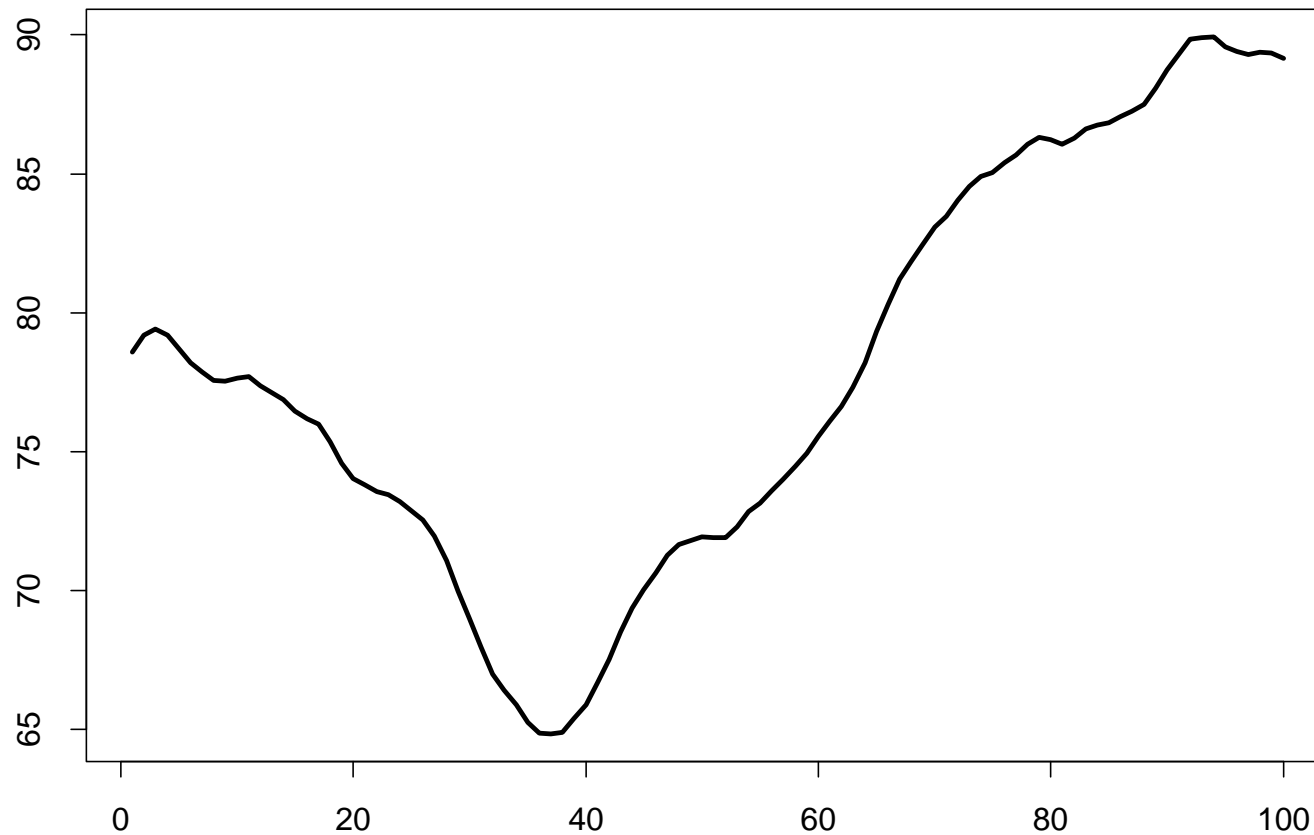
Variance of k -step prediction error:

$$\sigma_k^2 = (1 + \psi_1^2 + \cdots + \psi_{k-1}^2) \sigma_\varepsilon^2$$



Prediction of bond prices

$$(1 - 1.274B + 0.3867B^2)\nabla Y_t = \varepsilon_t; \quad \sigma_\varepsilon^2 = 0.201^2; \quad \mu_Y = 84.3$$





Prediction of bond prices

- Price last 6 days: ..., 90.79, 89.90, 88.88, 87.98, 87.41, 87.16
- Prediction of price in two days:

$$\begin{aligned}\varphi(B) &= \phi(B)\nabla = (1 + \phi_1 B + \phi_2 B^2)(1 - B) \\ &= 1 + (\phi_1 - 1)B + (\phi_2 - \phi_1)B^2 - \phi_2 B^3\end{aligned}$$

$$\hat{Y}_{t+1|t} = (1 - \phi_1)Y_t + (\phi_1 - \phi_2)Y_{t-1} + \phi_2 Y_{t-2} = 87.07$$

$$\hat{Y}_{t+2|t} = (1 - \phi_1)\hat{Y}_{t+1|t} + (\phi_1 - \phi_2)Y_t + \phi_2 Y_{t-1} = \underline{\underline{87.05}}$$

- Variance of prediction error:

$$V[\varepsilon_{t+2} + (1 - \phi_1)\varepsilon_{t+1}] = (1 + (1 - \phi_1)^2)\sigma_\varepsilon^2 = 0.500^2$$

- 95% prediction interval: $87.05 \pm 1.96 \cdot 0.50 = [86.07; 88.02]$